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COMMENT

Parallel dynamics for an extremely diluted neural network

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Abstract. We revise our formula for the main overlap evolution at t = 3 generated by the parallel dynamics in the symmetric extremely diluted neural network. We show that for $t \ge 3$ correlations between the Gaussian and the Bernoulli's 'memory-like' noises have to be taken into account. To derive the exact formula for t = 3 we use our previously developed truncated dynamics method.

In our paper [1] we claimed that the recursion relation (27)* (hereafter * denotes formulae from [1]) gives an exact formula for the evolution of the main overlap for parallel dynamics in the extremely diluted (symmetric) neural network. The last step in our calculations (transition from (26)* to (27)*) was incorrect: the 'memory-like' term $\xi_i^{(q)}s_i(t=1)g(t=2)$ and Gaussian noise $\sqrt{\alpha}\mathcal{N}(0,1)$ are correlated. The simplest way to take this correlation into account is as follows.

Let us represent the Gaussian part of the noise in $(26)^*$ (or in $(25)^*$) by using the 'truncated dynamics' [2]; then by definition $(11)^*$ and equations $(21)^*$, $(23)^*$, $(25)^*$, we get

where we use the 'truncated dynamics':

$$\widetilde{s}_{j}^{p}(t=2) = \operatorname{sgn}\left[\xi_{j}^{(q)}m_{N}^{(q)}(t=1) + \frac{1}{2c}\xi_{j}^{(p)}\sum_{k\in I_{j}\setminus i}\xi_{k}^{(p)}s_{k}(t=1) + \frac{1}{2c}\sum_{f(\neq p,q)}^{M}\xi_{j}^{(f)}\sum_{k\in I_{j}}\xi_{k}^{(f)}s_{k}(t=1)\right].$$
(2)

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Recall that for the 'memory-like' noise in (1) one has

$$\xi_i^{(q)} s_i(t=1) = \text{sgn}\left[m_N^{(q)}(0) + \frac{1}{2c} \xi_i^{(q)} \sum_{p(\neq q)}^M \xi_i^{(p)} \sum_{j \in I_i} \xi_j^{(p)} s_j(t=0) \right].$$
(3)

Then it becomes clear that it is correlated with the 'Gaussian-like' noise in (1) because variables $s_j(t=0)$ in (3) and $\tilde{s}_j^p(t=2)$ in (1) are correlated. Remark that 'truncated dynamics' (2) leaves $\{\xi_i^{(p)}\xi_j^{(p)}\tilde{s}_j^p(t=2)\}_{j,p}$ to be uncorrelated.

dynamics' (2) leaves $\{\xi_i^{(p)}\xi_j^{(p)}\tilde{s}_j^p(t=2)\}_{j,p}$ to be uncorrelated. Now let us define two subsets of I_i relevant to dynamics (2): $I_{i\pm} = \{j \in I_i : \tilde{s}_j^p(t=2)s_j(t=0) = \pm 1\}$. Then for the 'Gaussian-like' noise in (1) we get

where $p_{\pm} = \Pr\{\tilde{s}_j^p(t=2)s_j(t=0) = \pm 1\}$ and $\mathcal{N}_{\pm}(0,1)$ are independent Gaussian noises with zero mean and variance 1. Similarly we obtain for the noise in (3) that

$$`\alpha'-\lim \left\{ \frac{1}{2c} \xi_i^{(q)} \sum_{p(\neq q)}^M \xi_i^{(p)} \sum_{j \in I_i} \xi_j^{(p)} s_j(t=0) \right\} = \sqrt{\alpha p_+} \mathcal{N}_+(0,1) + \sqrt{\alpha p_-} \mathcal{N}_-(0,1).$$
(5)

Now, using representations (4), (5) and equations (1), (2), one gets

$$m^{(q)}(t=3) = \mathbb{E}(\xi_i^{(q)}s_i(t=3))$$

= $\frac{1}{2\pi} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} dx \, dy \, \exp[-(x^2 + y^2)/2] \, \operatorname{sgn}\{m^{(q)}(t=2) + g(t=2) +$

Formula (6) can be rewritten in the form

$$m^{(q)}(t=3) = \frac{1}{2\sqrt{2\pi\alpha}} \sum_{\sigma=\pm 1} \left[\int_{-\sigma g(t=2)-m^{(q)}(t=2)}^{+\infty} \mathrm{d}x - \int_{-\infty}^{-\sigma g(t=2)-m^{(q)}(t=2)} \mathrm{d}x \right]$$
$$\times \exp(-x^2/2\alpha) \left\{ 1 + \sigma \operatorname{erf}\left[\frac{(p_+ - p_-)x + m^{(q)}(t=0)}{2\sqrt{\alpha p_+ p_-}} \right] \right\}.$$
(7)

To calculate the probabilities p_{\pm} one has to use the representation (2) and equation (17)*. Then

$$\widetilde{s}_{j}^{p}(t=2)s_{j}(t=0) = `\alpha' - \lim \operatorname{sgn} \left\{ s_{j}(t=0)\xi_{j}^{(q)}m_{N}^{(q)}(t=1) + s_{j}(t=0)\frac{1}{2c}\xi_{j}^{(p)} \right. \\ \left. \times \sum_{k \in I_{j} \setminus i} \xi_{k}^{(p)}s_{k}(t=1) + s_{j}(t=0)\xi_{j}^{(q)}v_{j,I_{j}}^{p,q}(t=1) \right\}$$
(8)

where $v_{i,I_i}^{p,q}(t=1)$ is defined by (2). On the other hand by (17)^{*} we have

$${}^{\prime}\alpha' - \lim v_{j,l_j}^{p,q}(t=1) \stackrel{\mathrm{d}}{=} s_j(t=0)\xi_j^{(q)}g(t=1) + \sqrt{\alpha}\mathcal{N}(0,1)$$
(9)

where Gaussian and 'memory-like' noises are independent. Therefore, by (8) and (9) we obtain

$$\tilde{s}_{j}^{p}(t=2)s_{j}(t=0) = \operatorname{sgn}\{s_{j}(t=0)\xi_{j}^{(q)}m^{(q)}(t=1) + g(t=1) + \sqrt{\alpha}\mathcal{N}(0,1)\}.$$
(10)

Using (10) one gets

$$p_{+} = \Pr\{s_{j}(t=0)\xi_{j}^{(q)}m^{(q)}(t=1) + g(t=1) + \sqrt{\alpha}\mathcal{N}(0,1) > 0\}$$
$$= \frac{1}{2}\left\{1 + \sum_{\sigma=\pm 1} \frac{1 + \sigma m^{(q)}(0)}{2} \operatorname{erf}\left[\frac{\sigma m^{(q)}(t=1) + g(t=1)}{\sqrt{\alpha}}\right]\right\}$$
(11)

and $p_{-} = 1 - p_{+}$.

Substituting (11) in (7) gives the formula that (up to simplifications) coincides with the one for t = 3 obtained recently for the same model by Watkin and Sherrington [3] using the Gardner-Derrida-Mottishaw method [4].

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